

Current Work

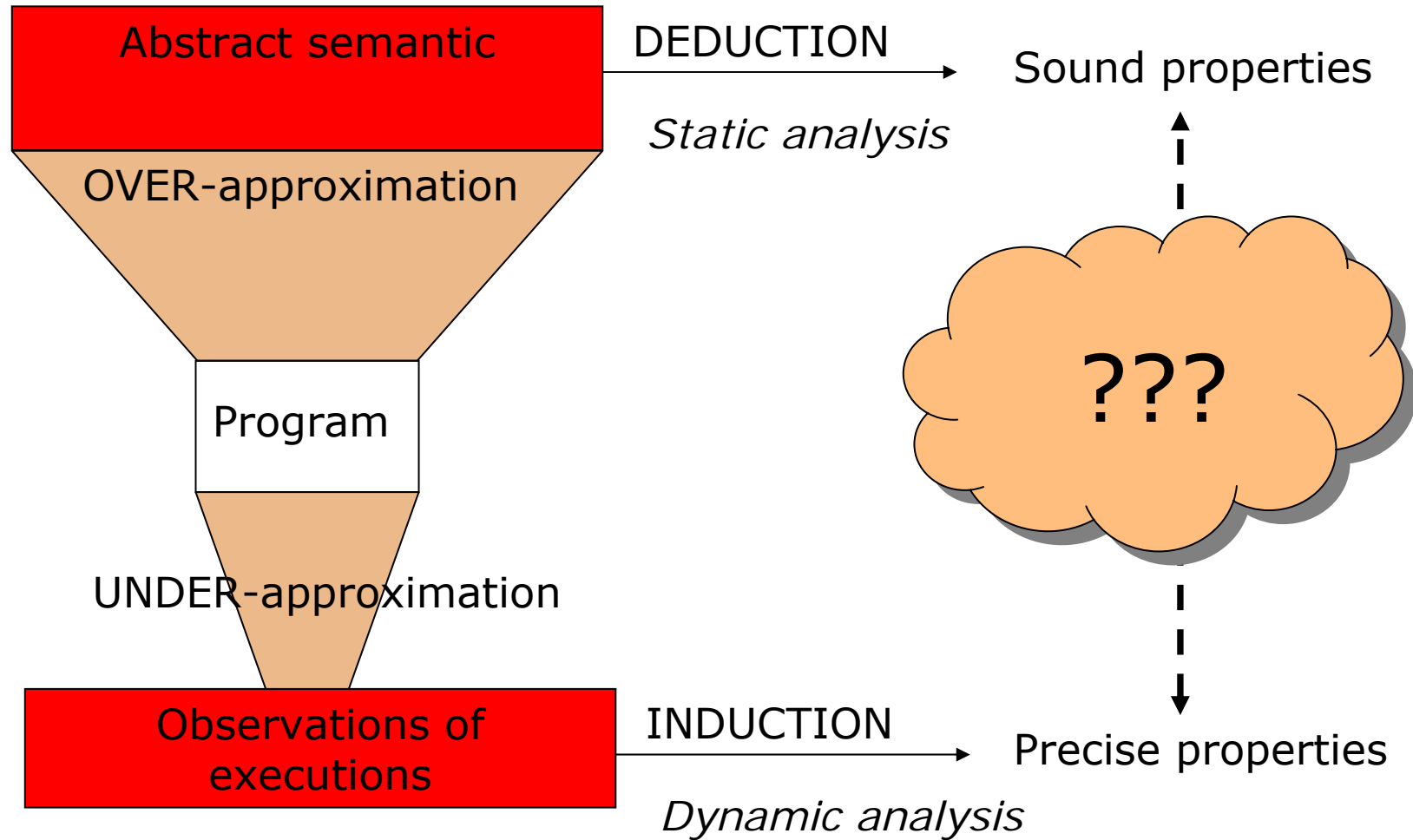
*Proving or Disproving  
Properties with  
Constraint Reasoning*

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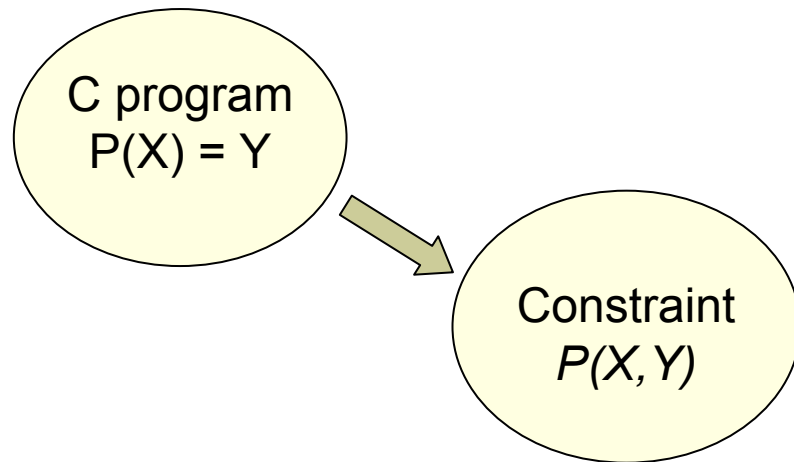
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WLPE 05 - Sitges

# *Inference of Program Properties*

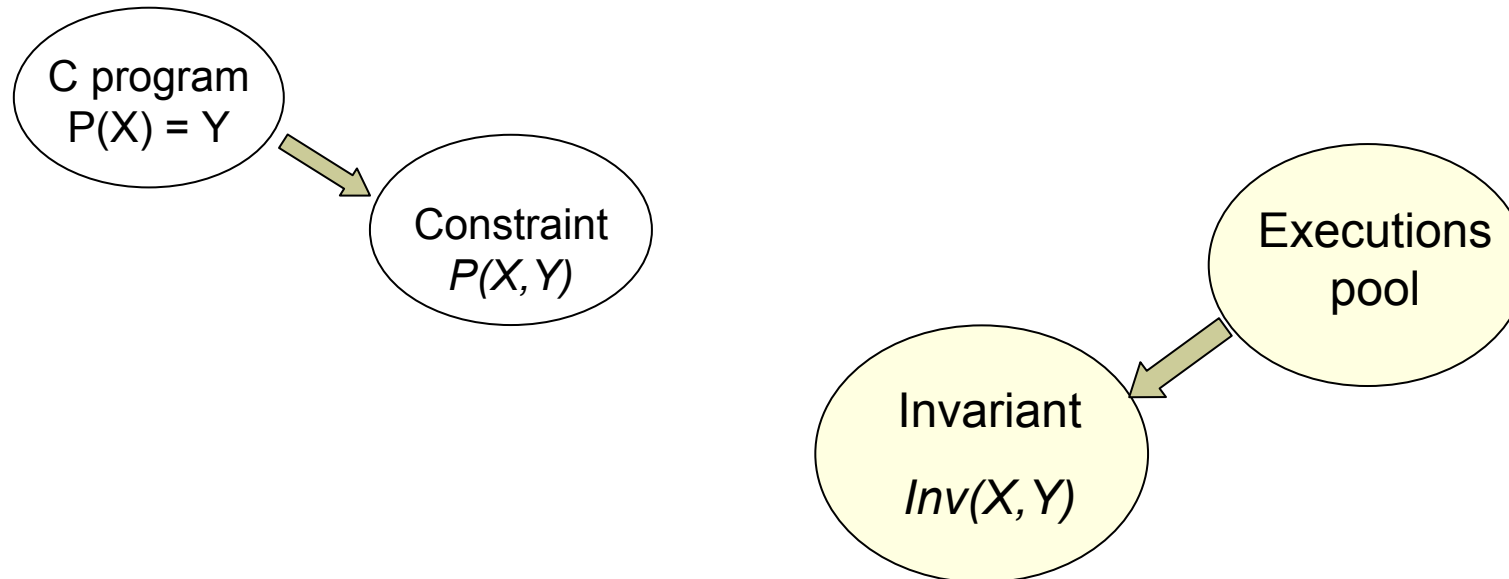


# *Our approach : 1-Modeling*



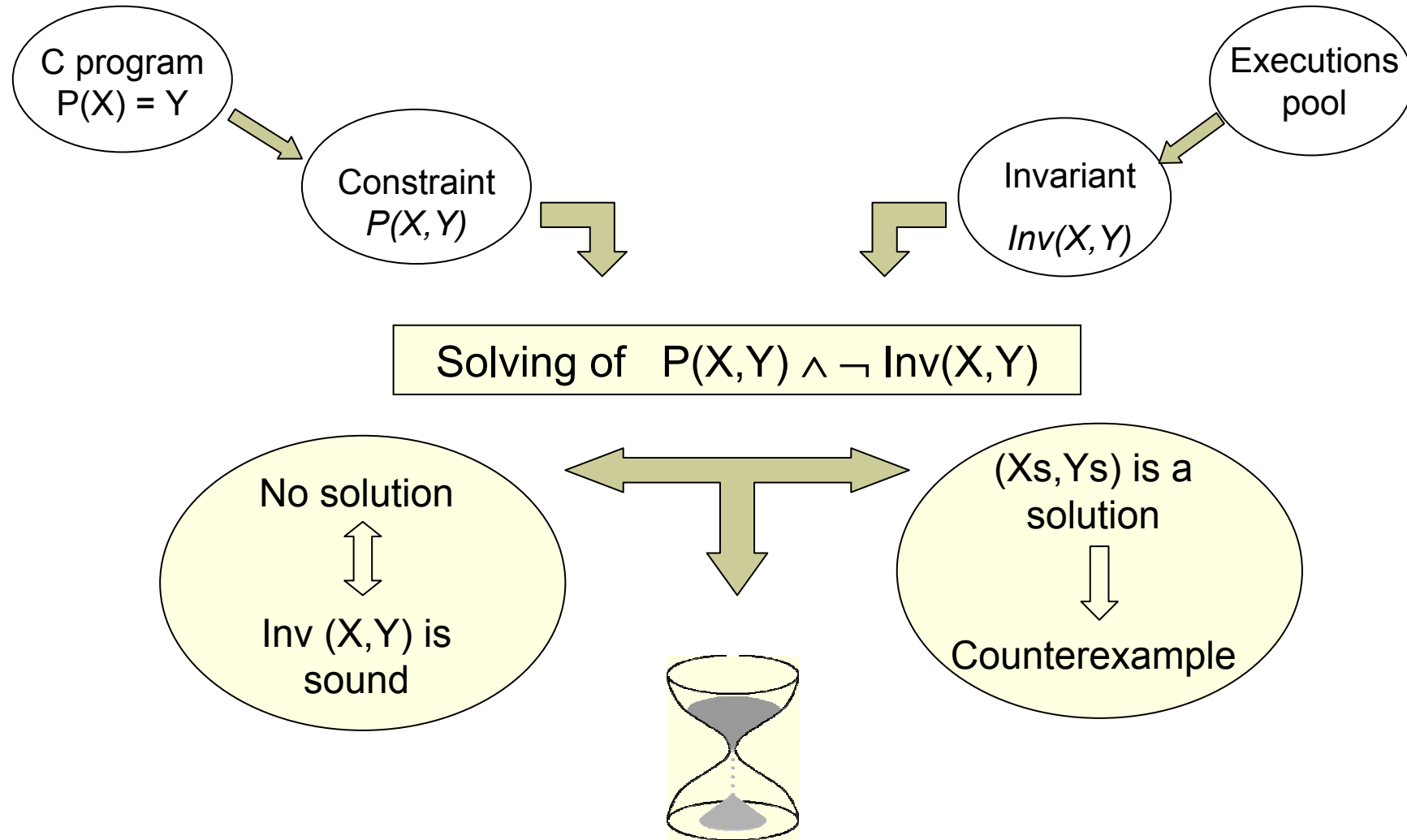
- Modeling of the relational semantics
  - $S[P] = \{(X, Y) \mid \text{there exists a trace } t \text{ with } \text{init}(t) = X \text{ and } \text{final}(t) = Y\}$
- Correct and complete
  - $P(X, Y) = \text{true} \Leftrightarrow (X, Y) \in S[P]$
- Implemented in Inka

# *Our approach : 2-Inducing*

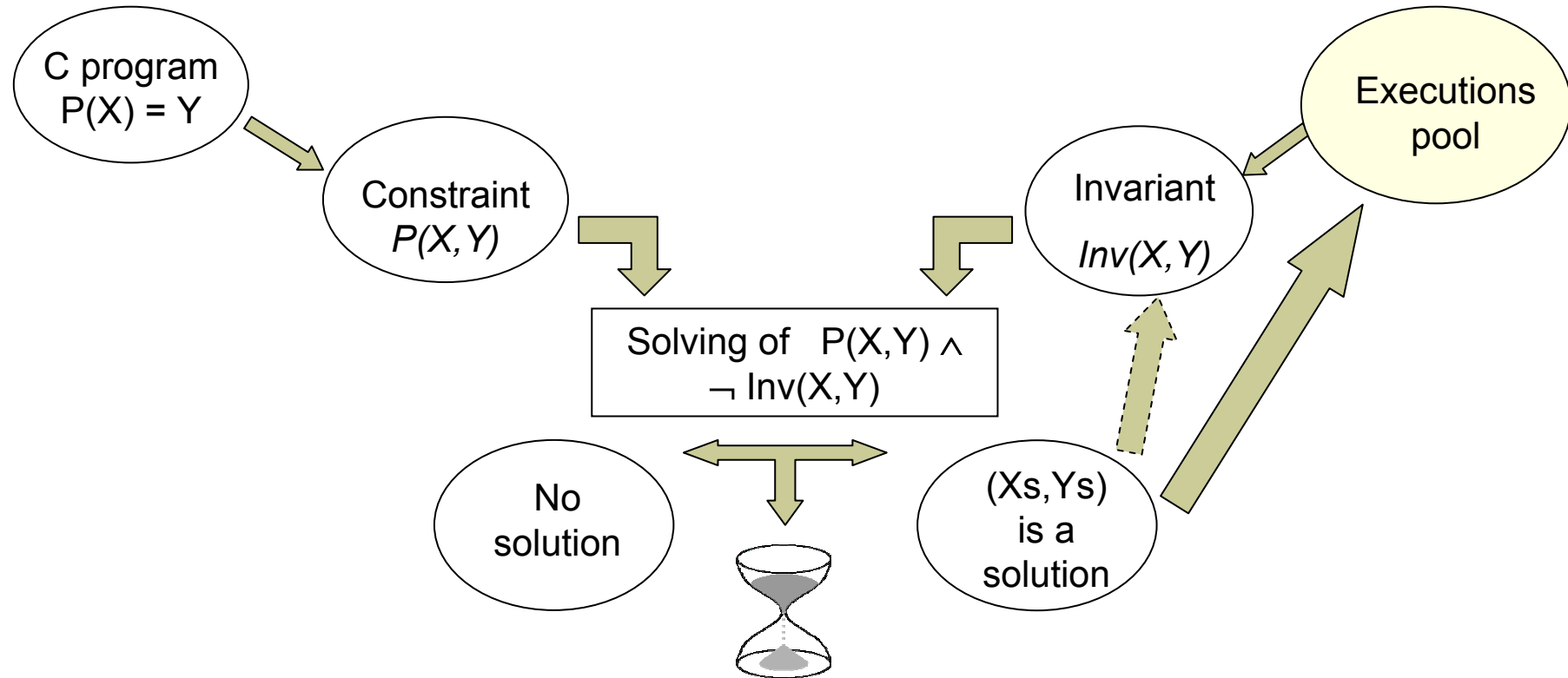


- Inference of an invariant (= property)
  - Relation between the memory states X and Y
- Could be a relation between intermediary states

# *Our approach : 3-Refuting*



# *Our approach : 4-Refining*



- Enlarge the pool of executions with the new one
- Maybe refine directly the invariant

## *Expected contributions*

- Obtain the correctness of dynamically inferred invariants
- Precise invariants due to the mechanism of refinement
- Potentially very large panel of invariants (all the relations !)

# *Outline*

- *Step 1* : Translation of an imperative program into CLP(FD)
- *Step 2* : Dynamic inference of properties  
(*Daikon as a black-box*)
- *Step 3* : Validation of properties
  - Motivating example
  - Problems and future work
  
- *No step 4 until now !!!*



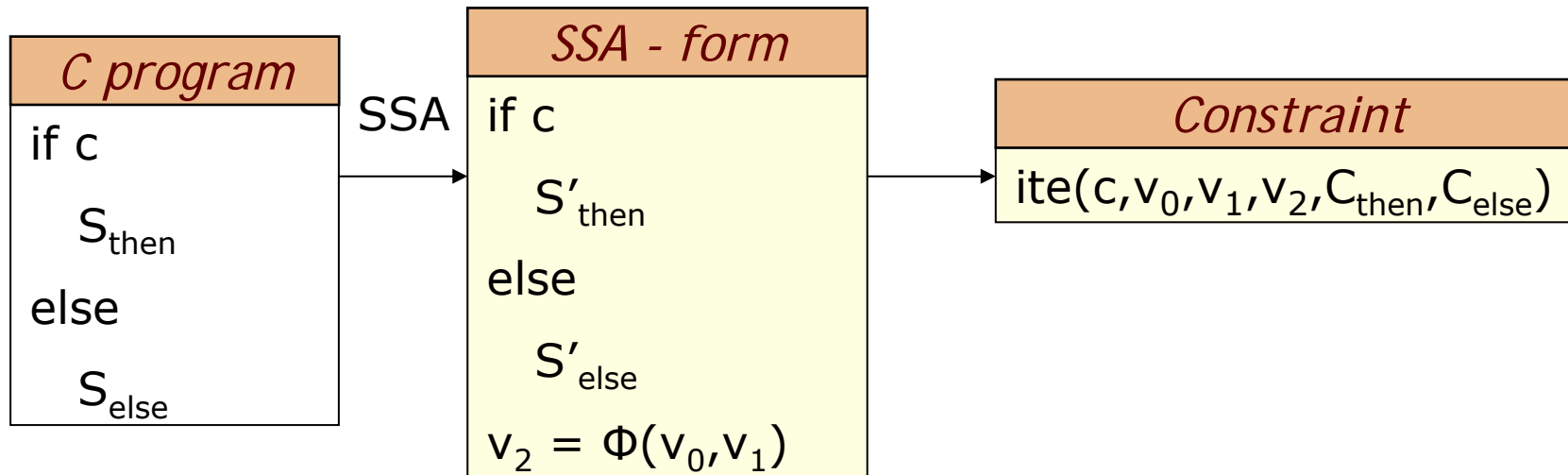
# *Constraint-model of a program*

- Translation of an imperative program into a constraint system
- 2 main problems
  - multiple assignments to a variable
  - conditionals and loops
- Approach of Gotlieb et al. [ISSTA 98]
  - SSA-Form
  - New constraint combinators

# *SSA Form*

- Translation of the program into SSA-form
  - Preserves the semantics
  - Each variable is assigned only once during execution
    - Except the iteration structures
  - Data flow is preserved via phi-functions
- Direct translation into constraints
  - A variable in the SSA form -> A logic variable
  - A control-structure -> A constraint

# "Ite" combinator

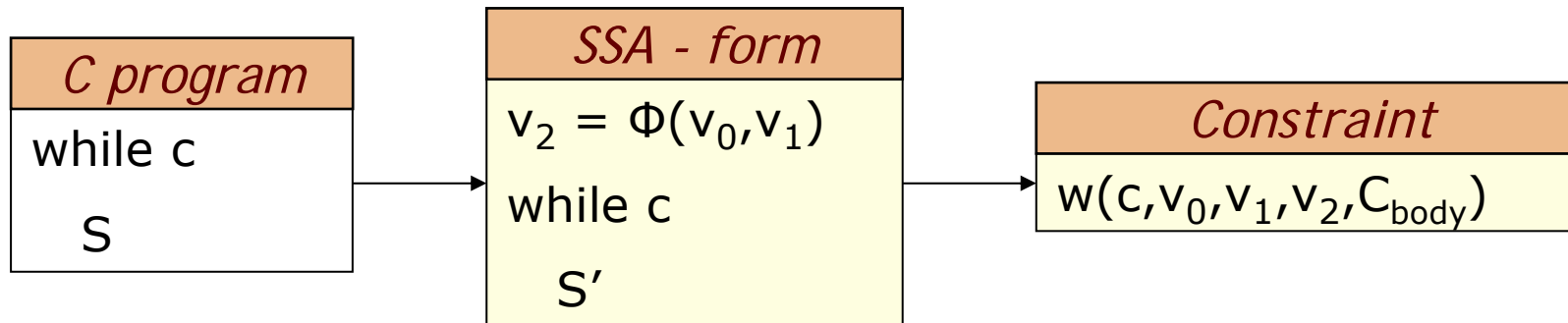


ite(c, v<sub>0</sub>, v<sub>1</sub>, v<sub>2</sub>, C<sub>then</sub>, C<sub>else</sub>):

Guarded constraints

$$\left\{ \begin{array}{l} \neg (c \wedge C_{\text{then}} \wedge v_2 = v_0) \rightarrow \neg c \wedge C_{\text{else}} \wedge v_2 = v_1 \\ \neg (\neg c \wedge C_{\text{then}} \wedge v_2 = v_1) \rightarrow c \wedge C_{\text{then}} \wedge v_2 = v_0 \end{array} \right.$$

# "W" Combinator



$W(c, v_0, v_1, v_2, C_{\text{body}})$  :

$$\neg (c \wedge C_{\text{body}}) \rightarrow \neg c \wedge v_2 = v_0$$

$$\neg (\neg c \wedge v_0 = v_2) \rightarrow c \wedge C_{\text{body}} \wedge w(c, v_1, v_3, v_2, C'_{\text{body}})$$

# *Dynamic inference of properties*

- We use Daikon as a black box, in its by default configuration [Ernst ICSE 99]
- Generate a set of potential relationships between variables of a program
  - At “interesting” points of the program
  - For “interesting” variables
- Run a test suite
- Consider relationships that hold over every test case as a *Likely Invariant*

# *Motivating example*

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

## *Likely invariants inferred*

- $\text{orig}(r) = 0 \Rightarrow \text{return} = 0$
- $\text{return} = 0 \Rightarrow \text{orig}(r) = 0$
- $\text{return} \geq \text{orig}(r)$

# *Validation of likely invariants*

- Problem of the Oracle :
  - Difficult to know if likely invariants hold
- Automatically checking these invariants is crucial
- Related work
  - Nimmer and Ernst 02 : based on a theorem prover
    - Proving properties
  - Vaziri and Jackson 00 : based on constraint solving
    - Disproving properties
- Our method :
  - Both proving and disproving invariants

# *Declarative semantics of invariant validation*

- Gopal Gupta [the LP paradigm 99]
  - Pre(X) : pre-condition on input vector X
  - P(X,Y) : denotation of an imperative program
    - Relation between input vector X and output vector Y
  - Post(X,Y) : post-condition
- Post condition is proved to hold if the following goal has no solution
  - Pre(X), P(X,Y), not Post(X,Y)



# *State space reduction with CLP*

- Using pure horn logic :
  - Generate and Test
  - Try all values of X such that  $\text{Pre}(X)$
- Using a CLP denotation :
  - Constrain – generate and Test
  - Asserting not  $\text{Post}(X, Y)$  reduces the search space
- Conjecture :
  - The reduction makes the approach more tractable

## *Running example - invariant 1*

■ Refutation of  $orig(r) = 0 \Rightarrow return = 0$

■  $foo(N, R, Ret) \wedge R = 0 \wedge Ret \neq 0$

Input domains reduction :

$N \in [1, sup], R = 0$

labeling step :

find a solution :  $N = 1, R = 0, Ret = 1$

■ Invariant 1 is disproved

## *Running example - invariant 2*

■ Refutation of  $return = 0 \Rightarrow orig(r) = 0$

■ **foo(N,R,Ret)  $\wedge$  Ret = 0  $\wedge$  R  $\neq$  0**

Input domains reduction :

$$N \in [1, \text{sup}], R \in [\text{inf}, -1] \cup [1, \text{sup}]$$

labeling step :

$$\text{find a solution : } N = 1, R = -1, \text{Ret} = 0$$

■ Invariant 2 is disproved

# *Comments*

- The labeling step is crucial to find counter examples
- In our two examples the default labeling procedure is “magically” efficient enough
  - For example, beginning to label variable R would have been terrible
- Future work
  - Design specialized heuristics for finding counter examples

## *Running example - invariant 3*

- Refutation of  $return \geq orig(r)$
- **foo(N,R,Ret)  $\wedge$  Ret < R**
  - Input domains reduction :  
 $N \in \emptyset, R \in \emptyset$
  - No labeling step
- Invariant 3 is proved

# *Details of the refutation 3*

Initial state

*Constraint store*

B = 0,  
w(...)  
RET < R

*Variables domains*

B in [0,0]  
N in [-100,100]  
R in [-99,100]  
RET in [-100,99]

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

# Details of the refutation 3

Propagation in the w combinator :  
entailment checking of the 2nd guard

$$\neg (\neg c \wedge v0 = v2) \rightarrow c \wedge Cbody \wedge w(c, v1, v3, v2, C'body)$$

<i>Constraint store</i>
B = 0, w(...) RET < R N =< 0, RET = R

<i>Variables domains</i>
B in [0,0] N in [-100,0] R in $\emptyset$ RET in $\emptyset$

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

Failure → the guard is entailed

# *Details of the refutation 3*

Propagation of the w combinator :

setting the tail of the constraint

$$\neg (\neg c \wedge v0 = v2) \rightarrow c \wedge Cbody \wedge w(c, v1, v3, v2, C'body)$$

## *Constraint store*

B = 0,  
w(...)  
RET < R  
N > 0  
N1 = N - 1  
B1 = 1  
R1 = R + 1

## *Variables domains*

B in [0,0]  
N in [1,100]  
R in [-99,99]  
RET in [-100,98]  
N1 in [0,99]  
B1 in [1,1]  
R1 in [-98,100]

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```



# *Details of the refutation 3*

Propagation in the w combinator :

entailment checking of the 2nd guard again

## *Constraint store*

B = 0,  
w(...)  
RET < R  
N > 0  
N1 = N - 1  
B1 = 1  
R1 = R + 1  
N1 =< 0  
RET = R1

## *Variables domains*

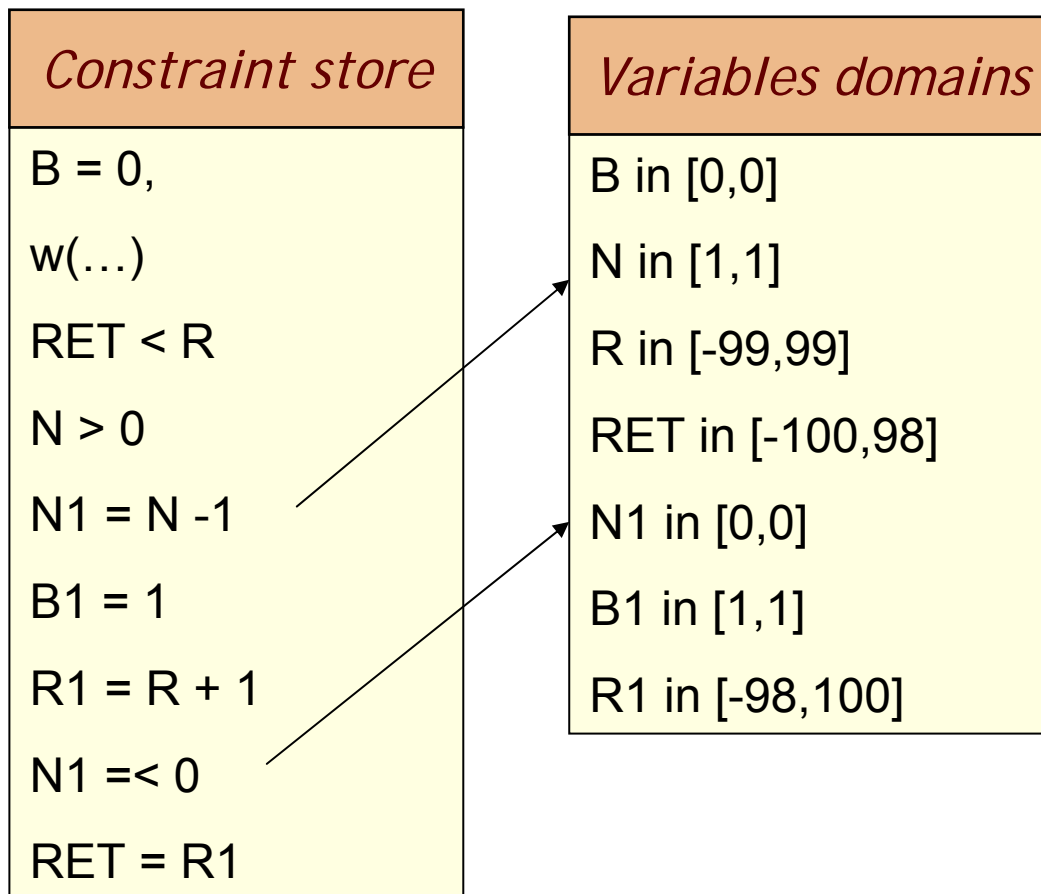
B in [0,0]  
N in [1,100]  
R in [-99,99]  
RET in [-100,98]  
N1 in [0,99]  
B1 in [1,1]  
R1 in [-98,100]

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

# *Details of the refutation 3*

Propagation in the w combinator :

entailment checking of the 2nd guard again



```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

# Details of the refutation 3

Propagation in the w combinator :

entailment checking of the 2nd guard again

<i>Constraint store</i>	<i>Variables domains</i>
B = 0,	B in [0,0]
w(...)	N in [1,1]
RET < R	R in [-99,99]
N > 0	RET in [-98,98]
N1 = N - 1	N1 in [0,0]
B1 = 1	B1 in [1,1]
R1 = R + 1	R1 in [-98,98]
N1 =< 0	
RET = R1	

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

# *Details of the refutation 3*

Propagation in the w combinator :

entailment checking of the 2nd guard again

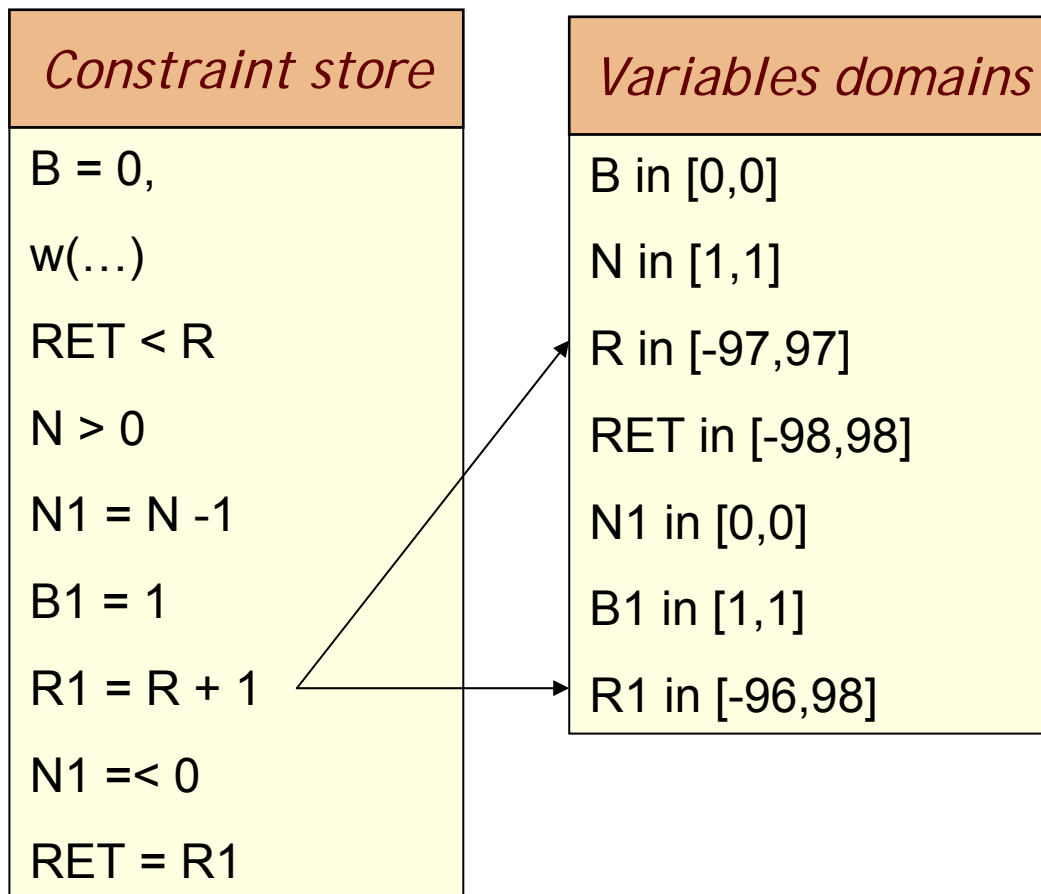
<i>Constraint store</i>	<i>Variables domains</i>
B = 0,	B in [0,0]
w(...)	N in [1,1]
RET < R	R in [-97,99]
N > 0	RET in [-98,98]
N1 = N - 1	N1 in [0,0]
B1 = 1	B1 in [1,1]
R1 = R + 1	R1 in [-98,98]
N1 =< 0	
RET = R1	

```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

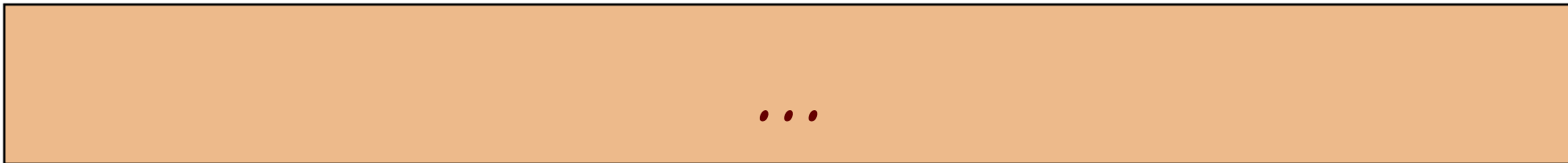
# Details of the refutation 3

Propagation in the w combinator :

entailment checking of the 2nd guard again



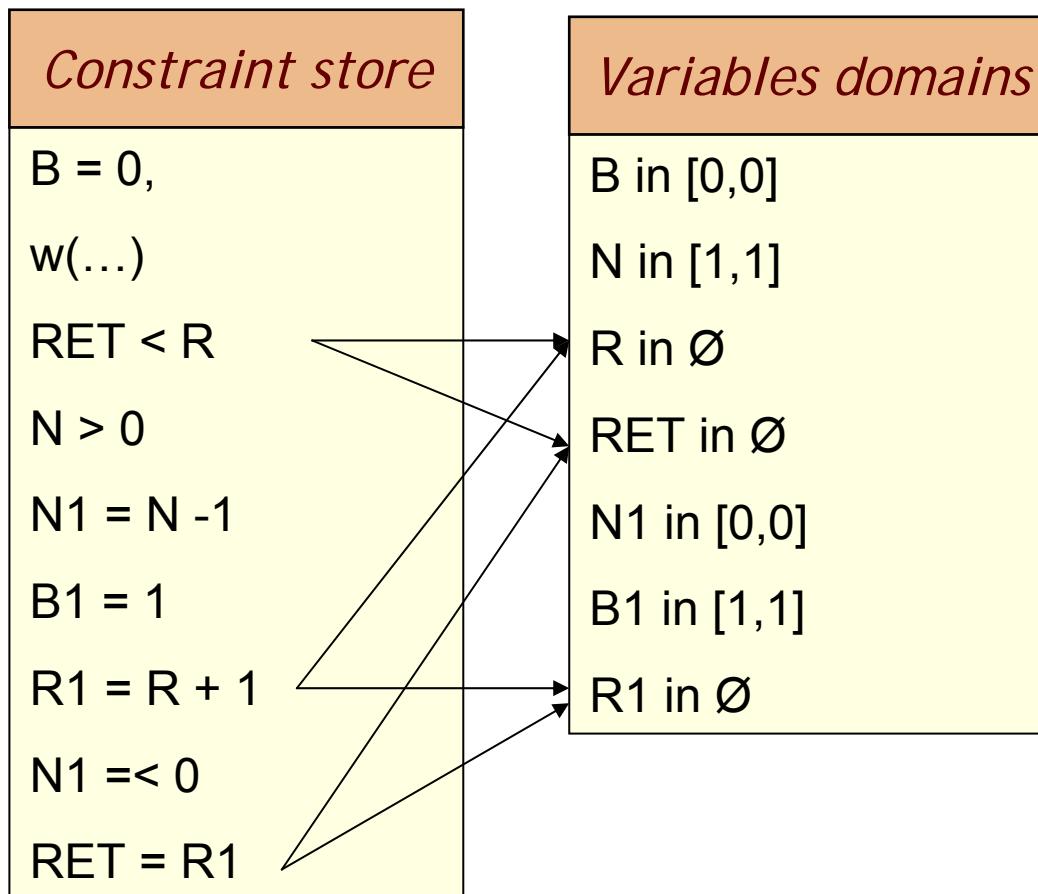
```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```



# Details of the refutation 3

Propagation in the w combinator :

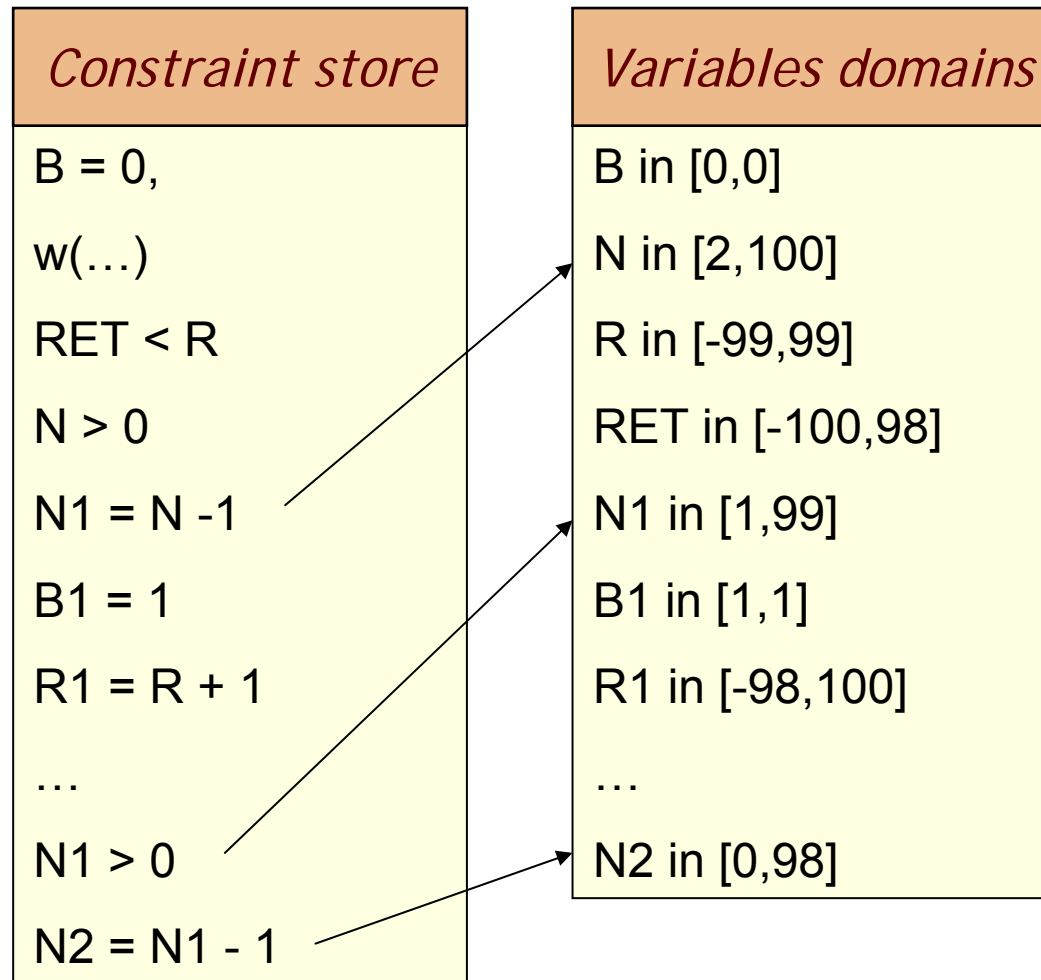
entailment checking of the 2nd guard again



```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```

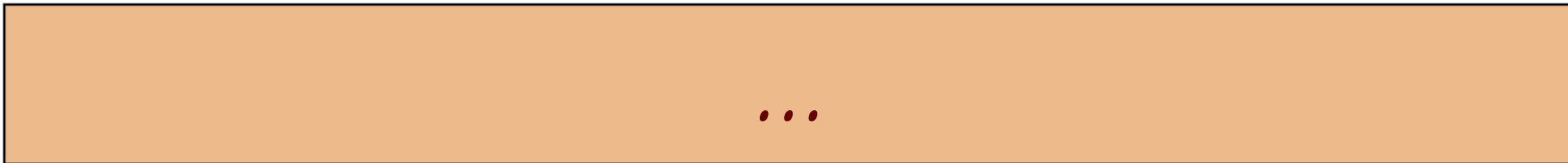
# Details of the refutation 3

Propagation of the w combinator : setting the tail of the constraint



```
int foo (int n, int r)
  b = 0;
  while (n > 0)
    if (b == 0)
      b = 1;
      r ++;
    else
      b = 0;
      r --;
  return r;
```





# *Details of the refutation 3*

## *Constraint store*

B = 0,  
w(...)  
RET < R  
N > 0  
N1 = N - 1  
B1 = 1  
R1 = R + 1  
...  
N1 > 0  
N2 = N1 - 1  
N100 = N99 - 1

## *Variables domains*

B in [0,0]  
N in [100,100]  
R in [-99,99]  
RET in [-100,98]  
N1 in [99,99]  
B1 in [1,1]  
R1 in [-98,100]  
...  
N2 in [98,98]  
N100 in [0,0]

We have a failure as it is impossible to unfold the loop and to exit the loop

# *Comments*

- The propagation is very long
  - We need to show inconsistencies at each loop unfolding
  - Each inconsistency is long to demonstrate
    - Bound consistency → slow convergence
- Future work
  - Use information about the loops such as loop invariants to add redundant constraint
  - Mix CLP(FD) with other types of constraint solver

# *Conclusion*

- An approach to both prove and disprove invariants based on constraints
  - No approximation
  - Based on clp(fd)
- Need to specialize constraint techniques to this particular problem
  - Propagation step
  - Labeling step